

# Nested sequents: Intermediate logics and neighbourhoods

Björn Lellmann

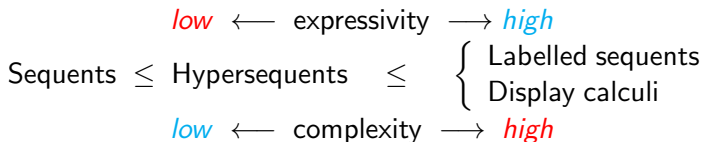
Logic Seminar Wien  
Oct 10, 2018

## General methods in proof theory

Recent development: general methods for constructing analytic calculi for non-classical logics in various frameworks. E.g.:

- ▶ Modal logics
  - ▶ Substructural logics
  - ▶ Intermediate logics
  - ▶ ...
- using
- ▶ Sequents
  - ▶ Hypersequents
  - ▶ Labelled sequents
  - ▶ Display calculi

By now these frameworks are (reasonably) well understood ...



## General methods in proof theory

Recent development: general methods for constructing analytic calculi for non-classical logics in various frameworks. E.g.:

- ▶ Modal logics
  - ▶ Substructural logics
  - ▶ Intermediate logics
  - ▶ ...
- using
- ▶ Sequents
  - ▶ Hypersequents
  - ▶ Labelled sequents
  - ▶ Display calculi

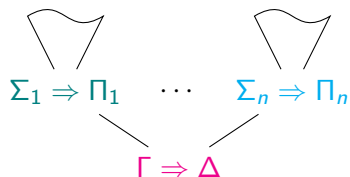
By now these frameworks are (reasonably) well understood ...

$$\begin{array}{c} \textit{low} \longleftarrow \text{expressivity} \longrightarrow \textit{high} \\ \text{Sequents} \leq \text{Hypersequents} \leq ? \leq \left\{ \begin{array}{l} \text{Labelled sequents} \\ \text{Display calculi} \end{array} \right. \\ \textit{low} \longleftarrow \text{complexity} \longrightarrow \textit{high} \end{array}$$

... But what about the stuff in between?

## Nested sequents

**Nested sequents** are trees of (multi-set based) sequents:



interpreted as  $\bigwedge \Gamma \rightarrow \bigvee \Delta \vee (\bigwedge \Sigma_1 \rightarrow \bigvee \Pi_1^*) \vee \dots \vee (\bigwedge \Sigma_n \rightarrow \bigvee \Pi_n^*)$

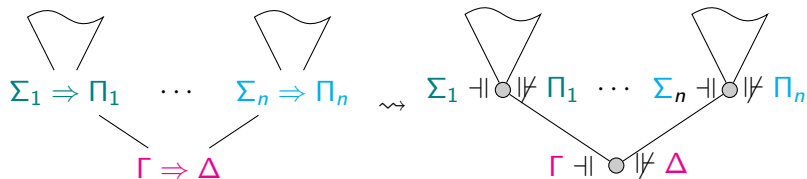
or  $\bigwedge \Gamma \rightarrow \bigvee \Delta \vee \square(\bigwedge \Sigma_1 \rightarrow \bigvee \Pi_1^*) \vee \dots \vee \square(\bigwedge \Sigma_n \rightarrow \bigvee \Pi_n^*)$ .

A bit of history:

- ▶ Precursors: [Bull:'92], [Kashima:'94], [Masini:'92]
- ▶ Current form in modal logics: [Brünnler:'09], [Poggiolesi:'09]
- ▶ For intuitionistic modal logics: [Straßburger et al:'12 - now]
- ▶ Adapted to intuitionistic logic in [Fitting:'14]

## Nested sequents

**Nested sequents** are trees of (multi-set based) sequents:



interpreted as  $\bigwedge \Gamma \rightarrow \bigvee \Delta \vee (\bigwedge \Sigma_1 \rightarrow \bigvee \Pi_1^*) \vee \dots \vee (\bigwedge \Sigma_n \rightarrow \bigvee \Pi_n^*)$

or  $\bigwedge \Gamma \rightarrow \bigvee \Delta \vee \Box(\bigwedge \Sigma_1 \rightarrow \bigvee \Pi_1^*) \vee \dots \vee \Box(\bigwedge \Sigma_n \rightarrow \bigvee \Pi_n^*)$ .

Nested sequents give rise to models for intuitionistic and modal logic.

But what about intermediate and non-normal modal logics?

## Part 1: Intermediate Logics

## Reminder: Intermediate logics

The **formulae** of intermediate logics are given by

$$p \in \text{Var} \mid \perp \mid \varphi \wedge \varphi \mid \varphi \vee \varphi \mid \varphi \rightarrow \varphi$$

A **frame**  $\mathcal{F} = (W, \preceq)$  has a reflexive transitive  $\preceq \subseteq W \times W$ .

**Valuations**  $\sigma$  satisfy:

- ▶ monotonicity:  $\mathcal{F}, \sigma, x \Vdash p$  and  $x \preceq y$  then  $\mathcal{F}, \sigma, y \Vdash p$
- ▶ local clauses for  $\wedge, \vee, \perp$
- ▶  $\mathcal{F}, \sigma, x \Vdash A \rightarrow B$  iff

$$\forall y (x \preceq y \Rightarrow (\mathcal{F}, \sigma, y \not\Vdash A \text{ or } \mathcal{F}, \sigma, y \Vdash B))$$

**Intermediate logics** are obtained by restricting the class of frames.

- ▶  $Bd_k$ : depth at most  $k$  ( $x_0 \preceq \dots \preceq x_k \Rightarrow \bigvee_{i=1}^k x_{i-1} = x_i$ )
- ▶  $GD$ : linear frames ( $x \preceq y \vee y \preceq x$ )
- ▶  $Jan$ : confluent frames ( $\exists z (x \preceq z \wedge y \preceq z)$ )
- ▶ ...

## Nested sequents for intuitionistic logic

Fitting's rules (applied **anywhere inside** the nested sequent):

$$\begin{array}{c}
 \begin{array}{c} \text{---} \\ \diagdown \quad \diagup \\ \Gamma \Rightarrow \Delta \end{array} \quad A \Rightarrow B \\
 \hline
 \begin{array}{c} \text{---} \\ \diagdown \quad \diagup \\ \Gamma \Rightarrow \Delta, A \rightarrow B \end{array} \quad \rightarrow_R
 \end{array}
 \qquad
 \begin{array}{c}
 \begin{array}{c} \text{---} \\ \diagdown \quad \diagup \\ \Gamma \Rightarrow \Delta, A \rightarrow B \end{array} \\
 \hline
 \begin{array}{c} \text{---} \\ \diagdown \quad \diagup \\ \Gamma \Rightarrow \Delta, \Sigma, A \Rightarrow \Pi \end{array} \quad \text{lift}
 \end{array}$$
  

$$\begin{array}{c}
 \begin{array}{c} \text{---} \\ \diagdown \quad \diagup \\ \Gamma, B \Rightarrow \Delta \end{array} \quad \begin{array}{c} \text{---} \\ \diagdown \quad \diagup \\ \Gamma \Rightarrow \Delta, A \end{array} \\
 \hline
 \begin{array}{c} \text{---} \\ \diagdown \quad \diagup \\ \Gamma, A \rightarrow B \Rightarrow \Delta \end{array} \quad \rightarrow_L
 \end{array}
 \qquad
 \begin{array}{c}
 \begin{array}{c} \text{---} \\ \diagdown \quad \diagup \\ \Gamma, A \Rightarrow \Delta \end{array} \\
 \hline
 \begin{array}{c} \text{---} \\ \diagdown \quad \diagup \\ \Sigma \Rightarrow \Pi \end{array}
 \end{array}$$

Together with local rules for  $\wedge, \vee, \perp$ , init, and contraction.

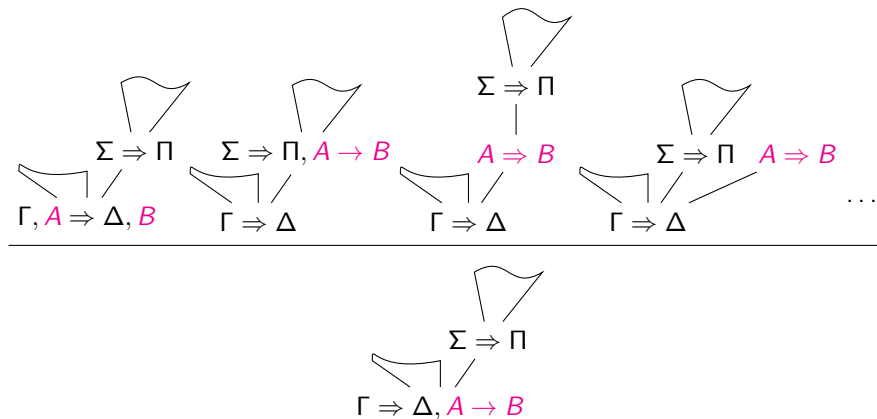
**Problem:** Rule  $\rightarrow_R$  loses control over the structure of the models.



## Our approach: Be more explicit

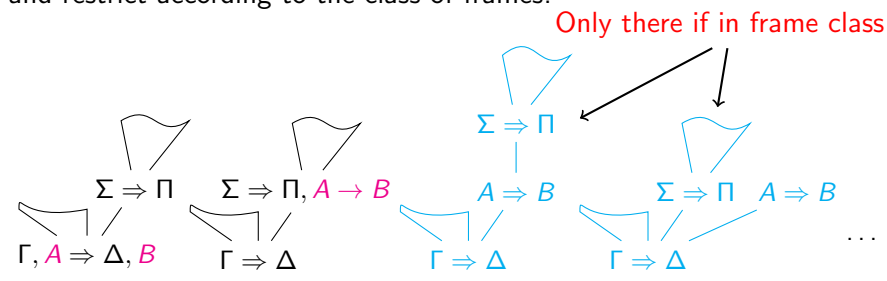
To regain control over the structure of the models we incorporate all different possibilities in the implication right rule

...



## Our approach: Be more explicit

To regain control over the structure of the models we incorporate all different possibilities in the implication right rule and restrict according to the class of frames!



## Injective nested sequents: Formally

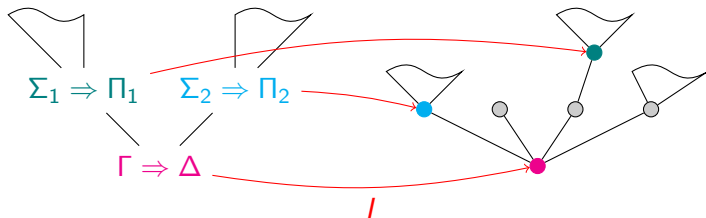
A **nested sequent** is a finite directed labelled tree  $(T, \nu)$ , written

$$\Gamma \Rightarrow \Delta, [S_1], \dots, [S_n]$$

with  $n \geq 0$  and  $S_i$  nested sequents.

Its **underlying tree** is the reflexive transitive closure  $T^*$  of  $T$ .

An **interpretation**  $I$  of a nested sequent in a tree-like model is a tree-embedding of its underlying tree into the model:



In particular, an interpretation is injective!

# The general rule scheme

The **restriction** of a set  $\mathcal{S}$  of nested sequents to a frame-class  $F$  is

$$\mathcal{S} \upharpoonright_F = \{ (T, \nu) \in \mathcal{S} \mid T^* \in F \}$$

For a suitable class  $F$  of frames, the  $\rightarrow_R^F$  rule is given by:

$$\frac{\left\{ \begin{array}{l} \nabla \{ \Gamma, A \Rightarrow B, A \rightarrow B, \Delta, [\Sigma_1 \Rightarrow \Pi_1^*], \dots, [\Sigma_n \Rightarrow \Pi_n^*] \} \\ \nabla \{ \Gamma \Rightarrow A \rightarrow B, \Delta, [\Sigma_1 \Rightarrow A \rightarrow B, \Pi_1^*], \dots, [\Sigma_n \Rightarrow \Pi_n^*] \} \\ \nabla \{ \Gamma \Rightarrow A \rightarrow B, \Delta, [A \Rightarrow B, [\Sigma_1 \Rightarrow \Pi_1^*]], \dots, [\Sigma_n \Rightarrow \Pi_n^*] \} \\ \vdots \\ \nabla \{ \Gamma \Rightarrow A \rightarrow B, \Delta, [\Sigma_1 \Rightarrow \Pi_1^*] \dots, [\Sigma_n \Rightarrow A \rightarrow B, \Pi_n^*] \} \\ \nabla \{ \Gamma \Rightarrow A \rightarrow B, \Delta, [\Sigma_1 \Rightarrow \Pi_1^*] \dots, [A \Rightarrow B, [\Sigma \Rightarrow \Pi^*]] \} \\ \nabla \{ \Gamma \Rightarrow A \rightarrow B, \Delta, [A \Rightarrow B], [\Sigma_1 \Rightarrow \Pi_1^*], \dots, [\Sigma_n \Rightarrow \Pi_n^*] \} \end{array} \right\} \upharpoonright_F}{\nabla \{ \Gamma \Rightarrow A \rightarrow B, \Delta, [\Sigma_1 \Rightarrow \Pi_1^*], \dots, [\Sigma_n \Rightarrow \Pi_n^*] \}} \rightarrow_R^F$$

## Example: Bounded depth $Bd_2$

Reminder:  $Bd_2$  frames have depth at most 2.

Thus the rules work only on nested sequents of depth  $\leq 2$ .

The rule with principal formula in the root:

$$\begin{array}{c}
 \begin{array}{ccc}
 \Sigma \Rightarrow \Pi & \Sigma \Rightarrow \Pi, A \rightarrow B & \Sigma \Rightarrow \Pi, A \Rightarrow B \\
 \diagdown \quad \diagup & \diagdown \quad \diagup & \diagdown \quad \diagup \quad \diagdown \\
 \Gamma, A \Rightarrow \Delta, B & \Gamma \Rightarrow \Delta & \Gamma \Rightarrow \Delta \quad \dots
 \end{array} \\
 \hline
 \begin{array}{c}
 \Sigma \Rightarrow \Pi \\
 \diagdown \quad \diagup \\
 \Gamma \Rightarrow \Delta, A \rightarrow B
 \end{array}
 \end{array}
 \xrightarrow{Bd_2_R}$$

And the rule with principal formula in a leaf:

$$\begin{array}{c}
 \begin{array}{c}
 \Sigma, A \Rightarrow \Pi, B \\
 \diagdown \quad \diagup \\
 \Gamma \Rightarrow \Delta
 \end{array} \\
 \hline
 \begin{array}{c}
 \Sigma \Rightarrow \Pi, A \rightarrow B \\
 \diagdown \quad \diagup \\
 \Gamma \Rightarrow \Delta
 \end{array}
 \end{array}
 \xrightarrow{Bd_2_R}$$

# Example: Gödel-Dummett logic *GD*

Reminder: *GD* frames are linear: every node has  $\leq 1$  successor.

$$\begin{array}{c}
 \vdots \\
 \Sigma \Rightarrow \Pi \\
 \vdots \\
 \Sigma \Rightarrow \Pi \quad A \Rightarrow B \quad \Sigma \Rightarrow \Pi, A \rightarrow B \\
 \vdots \quad \vdots \quad \vdots \\
 \Gamma, A \Rightarrow \Delta, B \quad \Gamma \Rightarrow \Delta \quad \Gamma \Rightarrow \Delta \\
 \vdots \quad \vdots \quad \vdots \\
 \hline
 \vdots \\
 \Sigma \Rightarrow \Pi \\
 \vdots \\
 \Gamma \Rightarrow \Delta, A \rightarrow B \\
 \vdots
 \end{array}
 \xrightarrow{GD_R}
 \begin{array}{c}
 A \Rightarrow B \\
 \vdots \\
 \Gamma, A \Rightarrow \Delta, B \quad \Gamma \Rightarrow \Delta \\
 \vdots \quad \vdots \\
 \hline
 \Gamma \Rightarrow \Delta, A \rightarrow B \\
 \vdots
 \end{array}
 \xrightarrow{GD_R}$$

## Example: Gödel-Dummett logic $GD$

Reminder:  $GD$  frames are linear: every node has  $\leq 1$  successor.

$$\begin{array}{c}
 \vdots \\
 \Sigma \Rightarrow \Pi \\
 | \\
 A \Rightarrow B \quad \Sigma \Rightarrow \Pi, A \rightarrow B \\
 | \qquad | \\
 \Gamma \Rightarrow \Delta \quad \Gamma \Rightarrow \Delta \\
 \vdots \qquad \vdots \\
 \hline
 \vdots \\
 \Sigma \Rightarrow \Pi \\
 | \\
 \Gamma \Rightarrow \Delta, A \rightarrow B \\
 \vdots
 \end{array}
 \xrightarrow{GD'_R}
 \begin{array}{c}
 A \Rightarrow B \\
 | \\
 \Gamma \Rightarrow \Delta \\
 \vdots \\
 \hline
 \Gamma \Rightarrow \Delta, A \rightarrow B \\
 \vdots
 \end{array}
 \xrightarrow{GD'_R}$$

Side note: In this case we can even omit more premisses.

Theorem (Kuznets-L.:AiML'18)

*This linear nested sequent calculus for  $GD$  has syntactic cut elimination.*

## Completeness and countermodels

For a frame class  $F$  the calculus  $G_F$  has the rule  $\rightarrow_R^F$ , Fitting's propositional and lift rules, and

$$\frac{\Gamma \Rightarrow B, \Delta^*, [\Sigma \Rightarrow B, \Pi^*]}{\Gamma \Rightarrow \Delta^*, [\Sigma \Rightarrow B, \Pi^*]} \text{Lwr} \quad \frac{\Gamma, A, A \Rightarrow B, A \rightarrow B, \Delta^*}{\Gamma, A \Rightarrow A \rightarrow B, \Delta^*} \rightarrow_R^*$$

### Theorem (Kuznets-L.)

*Let  $F$  consist of tree-like frames which are linear or of depth at most 2. Then  $G_F$  is sound and complete for  $F$ , and failed proof-search yields a countermodel.*

### Corollary

- ▶ Proof search for GD, Sm, BD<sub>2</sub>, GSc, CL is complexity-optimal.
- ▶ GD has the linear model property.



## Non-trivial application: Interpolation

A logic  $\mathcal{L}$  has **Craig interpolation** if whenever  $\mathcal{L} \vdash A(\vec{p}, \vec{q}) \rightarrow B(\vec{q}, \vec{r})$ , then there is an **interpolant**  $I(\vec{q})$  in the common language of  $A$  and  $B$  with

$$\mathcal{L} \vdash A(\vec{p}, \vec{q}) \rightarrow I(\vec{q}) \quad \text{and} \quad \mathcal{L} \vdash I(\vec{q}) \rightarrow B(\vec{q}, \vec{r})$$

It has **Lyndon interpolation** if the **polarities** of the  $\vec{q}$  are the same in  $A, B, I$ .

**Theorem (Maksimova:1977, nonconstructively)**

*There are exactly 7 intermediate logics with Craig interpolation.*

**Theorem (Kuznets-L.)**

*For GD, GSc, Sm, BD<sub>2</sub> the injective nested sequent calculi yield constructive proofs of Craig interpolation. For GD we also obtain Lyndon interpolation.*

## What do derivations look like?

... Let the implementation work that out!

## Part 2: Non-normal modal logics

# Monotone modal logic

The **formulae** of monotone modal logic M are given by

$$p \in \text{Var} \mid \perp \mid \varphi \wedge \varphi \mid \varphi \vee \varphi \mid \varphi \rightarrow \varphi \mid \langle \rangle \varphi$$

A **neighbourhood frame**  $\mathcal{F} = (W, \mathcal{N})$  has a **neighbourhood function** satisfying  $\mathcal{N}(w) \subseteq \mathcal{P}(W)$  for every  $w \in W$ .

**Valuations**  $\sigma$  satisfy:

- ▶ local clauses for  $\wedge, \vee, \rightarrow, \perp$ .
- ▶  $\mathcal{F}, \sigma, w \Vdash \langle \rangle A$  iff  $\exists \alpha \in \mathcal{N}(w) \forall v \in \alpha. \mathcal{F}, \sigma, v \Vdash A$

The **axiomatisation** of M is given by the rule

$$\frac{\vdash A \rightarrow B}{\vdash \langle \rangle A \rightarrow \langle \rangle B}$$

There is a linear nested sequent system for M [L-P'15]...

but it **lacks a formula interpretation and countermodel generation**

## What's the problem with the formula interpretation?

Interpreting the nesting of nested sequents with  $\tau$  and using Ackermann's Lemma we have the following equivalences:

$$\frac{\Gamma \Rightarrow \Delta, [\Rightarrow A] \quad \Gamma \Rightarrow \Delta, [\Rightarrow B]}{\Gamma \Rightarrow \Delta, [\Rightarrow A \wedge B]} \iff \overline{\tau(A) \wedge \tau(B) \Rightarrow \tau(A \wedge B)}$$
$$\frac{}{\Rightarrow [p \Rightarrow p]} \iff \overline{\Rightarrow \tau(p \rightarrow p)}$$
$$\frac{\Gamma \Rightarrow \Delta, [\Rightarrow A]}{\Gamma \Rightarrow \Delta, [\Rightarrow A \vee B]} \iff \overline{\tau(A) \Rightarrow \tau(A \vee B)}$$

Note that these are (equivalent to) the axioms of K. Hence:

**“Deep” admissibility of the propositional rules implies normality of the interpretation of the nesting operator!**

# monotone modal logic

The **formulae** of monotone modal logic  
are given by

$$p \in \text{Var} \mid \perp \mid \varphi \wedge \varphi \mid \varphi \vee \varphi \mid \varphi \rightarrow \varphi \mid \langle 1 \rangle \varphi$$

A **neighbourhood frame**  $\mathcal{F} = (W, \mathcal{N})$  has a **neighbourhood function** satisfying  $\mathcal{N}(w) \subseteq \mathcal{P}(W)$  for every  $w \in W$ .

**Valuations**  $\sigma$  satisfy:

- ▶ local clauses for  $\wedge, \vee, \rightarrow, \perp$ .
- ▶  $\mathcal{F}, \sigma, w \Vdash \langle 1 \rangle A$  iff  $\exists \alpha \in \mathcal{N}(w) \forall v \in \alpha. \mathcal{F}, \sigma, v \Vdash A$

# Bimodal monotone modal logic

The **formulae** of bimodal monotone modal logic aka. Brown's **Ability Logic** are given by

$$p \in \text{Var} \mid \perp \mid \varphi \wedge \varphi \mid \varphi \vee \varphi \mid \varphi \rightarrow \varphi \mid \langle \rangle \varphi \mid [] \varphi$$

A **neighbourhood frame**  $\mathcal{F} = (W, \mathcal{N})$  has a **neighbourhood function** satisfying  $\mathcal{N}(w) \subseteq \mathcal{P}(W)$  for every  $w \in W$ .

**Valuations**  $\sigma$  satisfy:

- ▶ local clauses for  $\wedge, \vee, \rightarrow, \perp$ .
- ▶  $\mathcal{F}, \sigma, w \Vdash \langle \rangle A$  iff  $\exists \alpha \in \mathcal{N}(w) \forall v \in \alpha. \mathcal{F}, \sigma, v \Vdash A$
- ▶  $\mathcal{F}, \sigma, w \Vdash [] A$  iff  $\forall \alpha \in \mathcal{N}(w) \forall v \in \alpha. \mathcal{F}, \sigma, v \Vdash A$

Brown's **ability interpretation** [Brown:'88]:

$\langle \rangle A$ : "The agent can reliably bring about  $A$ "

$[] A$ : "The agent will bring about  $A$ "

# Bimodal nested sequents

A **bimodal nested sequent** is a structure

$$\Gamma \Rightarrow \Delta, [S_1], \dots, [S_n], \langle \Sigma_1 \Rightarrow \Pi_1 \rangle, \dots, \langle \Sigma_m \Rightarrow \Pi_m \rangle$$

with  $n, m \geq 0$  where the  $S_i$  are bimodal nested sequents.

Its **formula interpretation**  $\iota$  is

$$\wedge \Gamma \rightarrow \vee \Delta \vee \bigvee_{i=1}^n \iota(S_i) \vee \bigvee_{j=1}^m \langle \iota(\wedge \Sigma_j \rightarrow \vee \Pi_j) \rangle$$



# The calculus for bimodal M

The calculus contains the (classical) propositional rules plus:

$$\frac{\Gamma \Rightarrow \Delta, [\Rightarrow A]}{\Gamma \Rightarrow \Delta, \langle \rangle A} \langle \rangle_R \quad \frac{\Gamma \Rightarrow \Delta, [\Sigma, A \Rightarrow \Pi]}{\Gamma, \langle \rangle A \Rightarrow \Delta, [\Sigma \Rightarrow \Pi]} \langle \rangle_L$$
$$\frac{\Gamma \Rightarrow \Delta, \langle \Rightarrow A \rangle}{\Gamma \Rightarrow \Delta, \langle \rangle A} \langle \rangle_R \quad \frac{\Gamma \Rightarrow \Delta, [\Sigma, A \Rightarrow \Pi]}{\Gamma, \langle \rangle A \Rightarrow \Delta, \langle \Sigma \Rightarrow \Pi \rangle} \langle \rangle_L$$
$$\frac{\Gamma \Rightarrow \Delta, [\Sigma \Rightarrow \Pi]}{\Gamma \Rightarrow \Delta, \langle \rangle A, \langle \Sigma \Rightarrow \Pi \rangle} W$$

Rules are applied **anywhere except inside  $\langle \cdot \rangle$** .

## Theorem

*The rules are sound wrt. the formula interpretation.*

# The calculus for bimodal M

The calculus contains the (classical) propositional rules plus:

$$\frac{\Gamma \Rightarrow \Delta, [\Rightarrow A]}{\Gamma \Rightarrow \Delta, \langle \rangle A} \langle \rangle_R \quad \frac{\Gamma \Rightarrow \Delta, [\Sigma, A \Rightarrow \Pi]}{\Gamma, \langle \rangle A \Rightarrow \Delta, [\Sigma \Rightarrow \Pi]} \langle \rangle_L$$
$$\frac{\Gamma \Rightarrow \Delta, \langle \Rightarrow A \rangle}{\Gamma \Rightarrow \Delta, \langle \rangle A} \langle \rangle_R \quad \frac{\Gamma \Rightarrow \Delta, [\Sigma, A \Rightarrow \Pi]}{\Gamma, \langle \rangle A \Rightarrow \Delta, \langle \Sigma \Rightarrow \Pi \rangle} \langle \rangle_L$$
$$\frac{\Gamma \Rightarrow \Delta, [\Sigma \Rightarrow \Pi]}{\Gamma \Rightarrow \Delta, \langle \rangle A, \langle \Sigma \Rightarrow \Pi \rangle} W$$

Rules are applied **anywhere except inside**  $\langle \cdot \rangle$ .

**Bonus:** Restricting the language specifies the calculus to the standard (linear) nested sequent calculus for **modal logic K**

# The calculus for bimodal M

The calculus contains the (classical) propositional rules plus:

$$\frac{\Gamma \Rightarrow \Delta, [\Rightarrow A]}{\Gamma \Rightarrow \Delta, [A]} [ ]_R \qquad \frac{\Gamma \Rightarrow \Delta, [\Sigma, A \Rightarrow \Pi]}{\Gamma, [A] \Rightarrow \Delta, [\Sigma \Rightarrow \Pi]} [ ]_L$$
$$\frac{\Gamma \Rightarrow \Delta, \langle \Rightarrow A \rangle}{\Gamma \Rightarrow \Delta, \langle A \rangle} \langle \rangle_R \qquad \frac{\Gamma \Rightarrow \Delta, [\Sigma, A \Rightarrow \Pi]}{\Gamma, \langle A \rangle \Rightarrow \Delta, \langle \Sigma \Rightarrow \Pi \rangle} \langle \rangle_L$$
$$\frac{\Gamma \Rightarrow \Delta, [\Sigma \Rightarrow \Pi]}{\Gamma \Rightarrow \Delta, [A], \langle \Sigma \Rightarrow \Pi \rangle} W$$

Rules are applied **anywhere except inside  $\langle \cdot \rangle$** .

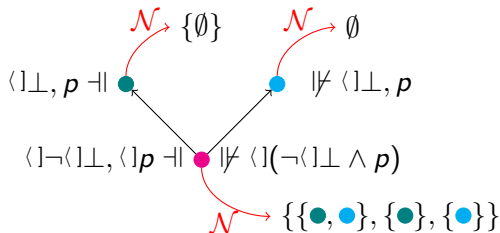
**Bonus:** Restricting the language specifies the calculus to the standard (linear) nested sequent calculus for modal logic K or the (linear) nested sequent calculus for **monomodal M**

## What about countermodels?

Using an annotated version of the calculus, underivable sequents give rise to countermodels: E.g.

$$\langle 1 \neg \langle 1 \perp, \langle 1 p \Rightarrow \langle 1 (\neg \langle 1 \perp \wedge \langle 1 p), [\langle 1 \perp, p \Rightarrow ], [\Rightarrow \langle 1 \perp, p ]$$

yields



### Theorem

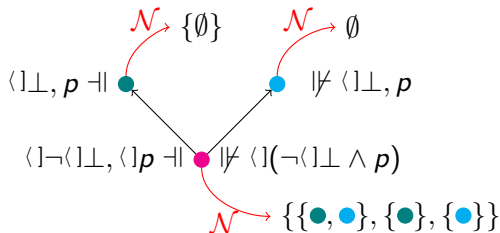
*The calculus for bimodal M is cut-free complete and failed proof search yields a countermodel.*

## What about countermodels?

Using an annotated version of the calculus, underivable sequents give rise to countermodels: E.g.

$$\langle 1 \neg \langle 1 \perp, \langle 1 p \Rightarrow \langle 1 (\neg \langle 1 \perp \wedge \langle 1 p), [\langle 1 \perp, p \Rightarrow ], [\Rightarrow \langle 1 \perp, p]$$

yields



### Corollary (Bonus)

*The calculi for K and monomodal M are cut-free complete and failed proof search yields a countermodel.*

## What do derivations look like?

... Let the implementation work that out!

## Suming up

**Injective nested sequents** for intermediate logics yield:

- ▶ uniform calculi for a number of logics based on semantics;
- ▶ optimal decision procedures with countermodel construction;
- ▶ constructive interpolation proofs.

**Bimodal nested sequents** for monotone modal logic yield:

- ▶ an internal calculus;
- ▶ support for countermodel construction;
- ▶ the basis for a general treatment of non-normal modal logics

Thank You!