

Interpolation for Intermediate Logics via Hyper- and Linear Nested Sequents

Roman Kuznets and Björn Lellmann

TU Wien

AiML 2018, Bern
August 28, 2018

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Classical

Intuitionistic



(mainly Gödel logic)

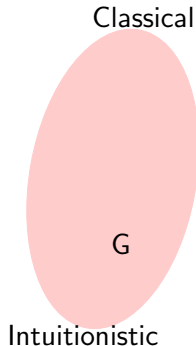


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Reminder: Interpolation for Intermediate Logics

Definition: A logic \mathcal{L} has **Craig interpolation** if whenever $\mathcal{L} \vdash A(\vec{p}, \vec{q}) \rightarrow B(\vec{q}, \vec{r})$, then there is an **interpolant** $I(\vec{q})$ in the common language of A and B with

$$\mathcal{L} \vdash A(\vec{p}, \vec{q}) \rightarrow I(\vec{q}) \quad \text{and} \quad \mathcal{L} \vdash I(\vec{q}) \rightarrow B(\vec{q}, \vec{r})$$

Theorem (Maksimova:1977)

There are exactly 7 intermediate logics with Craig interpolation.

But: Maksimova's proof is non-constructive.

Question: Can we extend **proof-theoretic methods** for constructing interpolants to these logics, in particular Gödel Logic G?

Reminder: Interpolation for Intermediate Logics

Definition: A logic \mathcal{L} has **Lyndon interpolation** if whenever $\mathcal{L} \vdash A(\vec{p}, \vec{q}) \rightarrow B(\vec{q}, \vec{r})$, then there is an **interpolant** $I(\vec{q})$ in the common language of A and B with

$$\mathcal{L} \vdash A(\vec{p}, \vec{q}) \rightarrow I(\vec{q}) \quad \text{and} \quad \mathcal{L} \vdash I(\vec{q}) \rightarrow B(\vec{q}, \vec{r})$$

such that the **polarities** of the \vec{q} are the same in A, B, I .

Theorem (Maksimova:2014)

The logics Int, KC, LP₂, LS, CI have Lyndon-interpolation.

Question: What about the other two, in particular **Gödel logic** G?

Gödel logic

The **formulae** of intermediate logics are given by

$$\Phi ::= \text{Var} \mid \perp \mid \top \mid \Phi \vee \Phi \mid \Phi \wedge \Phi \mid \Phi \rightarrow \Phi$$

Negation is defined as $\neg A \equiv A \rightarrow \perp$.

Frames are tuples (W, \leq) where $\leq \subseteq W \times W$ is reflexive, transitive and antisymmetric. A **model** \mathcal{M} extends a frame by a **valuation** $V : W \rightarrow 2^{\text{Var}}$ with $w \leq v \Rightarrow V(w) \subseteq V(v)$.

Truth of a formula is written $\mathcal{M}, w \Vdash A$ and defined by

$$\mathcal{M}, w \Vdash A \rightarrow B \quad \text{iff} \quad \forall v \geq w (\mathcal{M}, v \not\Vdash A \text{ or } \mathcal{M}, v \Vdash B)$$

Gödel logic G is the set of formulae valid in all **linear** frames, i.e., frames with: $\forall v, w (v \leq w \text{ or } w \leq v)$

What about Hypersequents?

A **hypersequent** is a finite multiset $\Gamma_1 \Rightarrow \Delta_1 \mid \dots \mid \Gamma_n \Rightarrow \Delta_n$ of sequents with **formula interpretation**

$$(\bigwedge \Gamma_1 \rightarrow \bigvee \Delta_1) \vee \dots \vee (\bigwedge \Gamma_n \rightarrow \bigvee \Delta_n).$$

The hypersequent calculus for G has the **communication rule**:

$$\frac{\mathcal{G} \mid \Gamma_1, \Gamma_2 \Rightarrow \Delta \quad \mathcal{G} \mid \Sigma_1, \Sigma_2 \Rightarrow \Pi}{\mathcal{G} \mid \Gamma_1, \Sigma_1 \Rightarrow \Delta \mid \Gamma_2, \Sigma_2 \Rightarrow \Pi} \text{com}$$

Intuition: “Pick the larger world” (bottom-up)

What about Hypersequents?

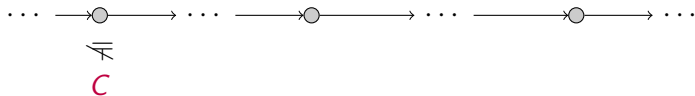
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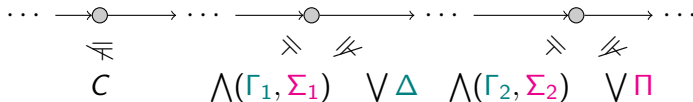
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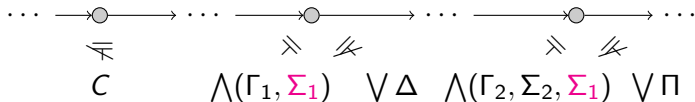
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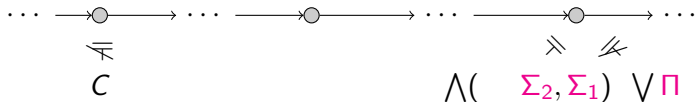
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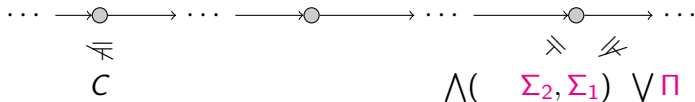
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Problem for interpolation: this forgets the structure of the worlds

Can we keep the structure of linear models?

Linear nested sequents for G

A **Linear nested sequent** is a finite list of sequents

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The calculus **LNS_G** contains the implication-right rule

$$\frac{\mathcal{G} // \Gamma \Rightarrow \Delta // A \Rightarrow B // \Sigma \Rightarrow \Pi // \mathcal{H} \quad \mathcal{G} // \Gamma \Rightarrow \Delta // \Sigma \Rightarrow \Pi, A \rightarrow B // \mathcal{H}}{\mathcal{G} // \Gamma \Rightarrow \Delta, A \rightarrow B // \Sigma \Rightarrow \Pi // \mathcal{H}} \rightarrow_R^2$$

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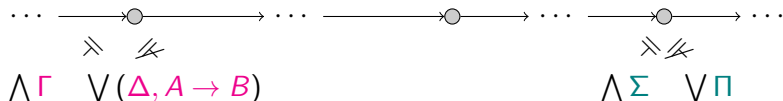
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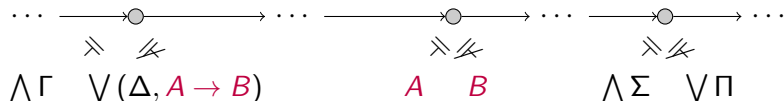
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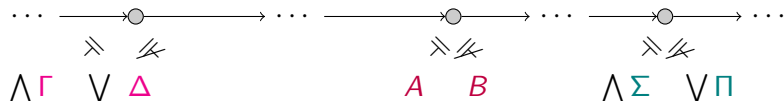
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... hence the structure of the interpolants can be preserved!

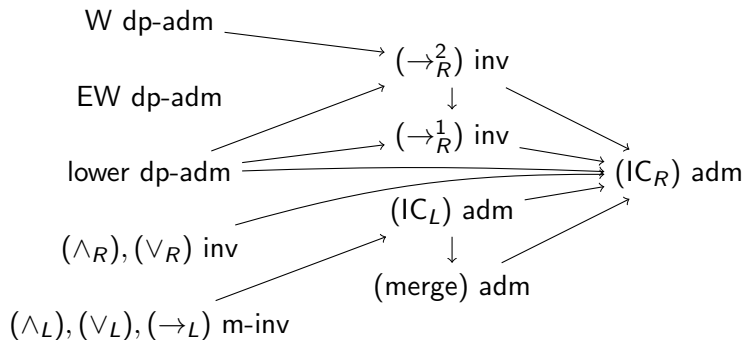
Soundness and cut-free completeness

Theorem (KL:2018)

LNS_G is sound and complete for G .

Proof idea: Soundness as usual.

Completeness via a series of admissibility and invertibility lemmas followed by cut elimination:



But what about interpolation?

Interpolation proof-theoretically

Sequent case

- ▶ Find interpolants for each sequent in a sequent derivation top-to-bottom
- ▶ Interpolants are formulas
- ▶ Interpolation statement can be represented as two sequents

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Generalized sequents,

e.g., linear nested sequents, hypersequents, etc.

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Semantics respecting linear nested structure

$$\mathcal{M}, w_1, \dots, w_n \models \Gamma_1 \Rightarrow \Delta_1 // \dots // \Gamma_n \Rightarrow \Delta_n$$

\iff

$$(\exists A_i \in \Gamma_i) \quad w_i \not\models A_i \quad \text{or} \quad (\exists B_i \in \Delta_i) \quad w_i \models B_i$$

where $w_1 \leq \dots \leq w_n$ are worlds from linear \mathcal{M}

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Theorem (Completeness, KL:2018)

$$\text{LNS}_G \vdash \Gamma_1 \Rightarrow \Delta_1 // \dots // \Gamma_n \Rightarrow \Delta_n$$

iff

$$(\forall \text{linear } \mathcal{M})(\forall w_1 \leq \dots \leq w_n \in \mathcal{M}) \\ \mathcal{M}, w_1, \dots, w_n \models \Gamma_1 \Rightarrow \Delta_1 // \dots // \Gamma_n \Rightarrow \Delta_n$$

Interpolants of formulas evaluated at different worlds

Already used for classical hypersequents, nested sequents, etc.

For $w_1 \leq \dots \leq w_n \in \mathcal{M}$ for a linear model \mathcal{M}

$$w_1, \dots, w_n \vDash A^{(i)} \quad \text{iff} \quad w_i \Vdash A$$

$$w_1, \dots, w_n \vDash \mathcal{U}_1 \otimes \mathcal{U}_2 \quad \text{iff} \quad w_1, \dots, w_n \vDash \mathcal{U}_1 \text{ and } w_1, \dots, w_n \vDash \mathcal{U}_2$$

$$w_1, \dots, w_n \vDash \mathcal{U}_1 \oplus \mathcal{U}_2 \quad \text{iff} \quad w_1, \dots, w_n \vDash \mathcal{U}_1 \text{ or } w_1, \dots, w_n \vDash \mathcal{U}_2$$

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New for intuitionistic case

$$w_1, \dots, w_n \models \overline{A}^{(i)} \quad \text{iff} \quad w_j \not\vdash A$$

(Classically, $\overline{A}^{(i)}$ is expressible as $(\neg A)^{(i)}$.)

Componentwise interpolation statement

Definition

A multiformula \mathcal{U} **componentwise interpolates** (CW-interpolates) a split linear nested sequent

$$\Gamma_1; \Pi_1 \Rightarrow \Delta_1; \Sigma_1 // \dots // \Gamma_n; \Pi_n \Rightarrow \Delta_n; \Sigma_n$$

iff

- ▶ \mathcal{U} only uses $A^{(k)}$ and $\bar{A}^{(k)}$ with $k \leq n$;
- ▶ \mathcal{U} only uses positive (negative) propositional atoms that occur positively (negatively) in both

$$\Gamma_1 \Rightarrow \Delta_1 // \dots // \Gamma_n \Rightarrow \Delta_n \quad \text{and} \quad \Pi_1 \Rightarrow \Sigma_1 // \dots // \Pi_n \Rightarrow \Sigma_n;$$

- ▶ for any $w_1 \leq \dots \leq w_n$ in a linear frame

$$w_1, \dots, w_n \not\models \mathcal{U} \quad \Longrightarrow \quad w_1, \dots, w_n \models \Gamma_1 \Rightarrow \Delta_1 // \dots // \Gamma_n \Rightarrow \Delta_n;$$

$$w_1, \dots, w_n \models \mathcal{U} \quad \Longrightarrow \quad w_1, \dots, w_n \models \Pi_1 \Rightarrow \Sigma_1 // \dots // \Pi_n \Rightarrow \Sigma_n.$$

Componentwise interpolation example

$$p; \Rightarrow // \Rightarrow; p //; q \Rightarrow; q \leftarrow p^{(1)}$$

$$p; \Rightarrow // \Rightarrow; p //; q \Rightarrow; q \leftarrow p^{(2)}$$

$$p; \Rightarrow // \Rightarrow; p //; q \Rightarrow; q \leftarrow p^{(3)}$$

$$p; \Rightarrow // \Rightarrow; p //; q \Rightarrow; q \leftarrow q^{(3)}$$

Express your interpolant

Question

Isn't this **more** expressive than propositional language?

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Honest answer

Yes, most componentwise interpolation statements **cannot** be expressed in the object language.

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Yes, most componentwise interpolation statements cannot be expressed in the object language.

But...

Useful answer

$\bigcirc_{i=1}^m (\overline{C}_i^{(1)} \vee D_i^{(1)})$ is a CW-interpolant of $A; \Rightarrow; B$

implies

$\bigwedge_{i=1}^m (C_i \rightarrow D_i)$ is a Lyndon interpolant of $A \rightarrow B$.

Applications of the method

To linear nested sequents

Gödel logic (of linear frames) has Lyndon interpolation. (KL:2018)

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Bonus: To hypersequents (with appropriate modifications)

Jankov logic (of weak excluded middle) has Lyndon interpolation.
(Maksimova:2014; constructively: KL:2018)

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Future Bonus: To other cool formalisms

Tune in for further announcements

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Interesting fact

Applying the method to well-known hypersequents for **Gödel logic** does not succeed:

$$\frac{p; \Rightarrow p; \quad ; q \Rightarrow ; q}{; q \Rightarrow p; \mid p; \Rightarrow ; q}$$

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Applying the method to well-known hypersequents for Gödel logic does not succeed:

$$\frac{p; \Rightarrow p; \quad ; q \Rightarrow ; q}{; q \Rightarrow p; \mid p; \Rightarrow ; q}$$

Thus, CW interpolation is strictly stronger than Lyndon one.

Thank you

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Simple interpolation transformation

$$\frac{\tilde{\mathcal{G}} // \tilde{\Gamma} \Rightarrow \Delta; \Pi //; A \Rightarrow; B \leftarrow \bigotimes_{j=1}^m \left(\overline{C}_j^{(n)} \otimes D_j^{(n)} \otimes \bigotimes_{l=1}^{n-1} (\overline{E}_{jl}^{(l)} \otimes F_{jl}^{(l)}) \right)}{\tilde{\mathcal{G}} // \tilde{\Gamma} \Rightarrow \Delta; \Pi, A \rightarrow B \leftarrow \bigotimes_{j=1}^m \left((C_j \rightarrow D_j)^{(n-1)} \otimes \bigotimes_{l=1}^{n-1} (\overline{E}_{jl}^{(l)} \otimes F_{jl}^{(l)}) \right)}$$

Complex interpolation transformation

$$\begin{array}{c}
 \tilde{\mathcal{G}} // \tilde{\Gamma} \Rightarrow \Delta; \Theta // \tilde{\Sigma} \Rightarrow \Pi; \Lambda, A \rightarrow B // \tilde{\mathcal{H}} \leftarrow \mathcal{U} \\
 \tilde{\mathcal{G}} // \tilde{\Gamma} \Rightarrow \Delta; \Theta //; A \Rightarrow; B // \tilde{\Sigma} \Rightarrow \Pi; \Lambda // \tilde{\mathcal{H}} \leftarrow \bigotimes_{j=1}^m \left(\overline{C}_j^{(n)} \otimes D_j^{(n)} \otimes \bigotimes_{l \neq n} (\overline{E}_{jl}^{(l)} \otimes F_{jl}^{(l)}) \right) \\
 \hline
 \leftarrow \mathcal{U} \otimes \bigotimes_{j=1}^m \left(\bigotimes_{l=1}^{n-1} (\overline{E}_{jl}^{(l)} \otimes F_{jl}^{(l)}) \otimes (C_j \rightarrow D_j)^{(n-1)} \otimes \overline{C}_j^{(n)} \otimes \bigotimes_{l=n}^{n+k} (\overline{E}_{j,l+1}^{(l)} \otimes F_{j,l+1}^{(l)}) \right) \\
 \tilde{\mathcal{G}} // \tilde{\Gamma} \Rightarrow \Delta; \Theta, A \rightarrow B // \tilde{\Sigma} \Rightarrow \Pi; \Lambda // \tilde{\mathcal{H}} \quad \leftarrow
 \end{array}$$

The LNS system

The system LNS_G is based on [Fitting:2014, Indrzejczak:2016].

Some further rules:

$$\frac{\mathcal{G} // \Gamma \Rightarrow \Delta // A \Rightarrow B}{\mathcal{G} // \Gamma \Rightarrow \Delta, A \rightarrow B} \rightarrow_R^1$$

$$\frac{\mathcal{G} // \Gamma \Rightarrow \Delta // A \Rightarrow B // \Sigma \Rightarrow \Pi // \mathcal{H} \quad \mathcal{G} // \Gamma \Rightarrow \Delta // \Sigma \Rightarrow \Pi, A \rightarrow B // \mathcal{H}}{\mathcal{G} // \Gamma \Rightarrow \Delta, A \rightarrow B // \Sigma \Rightarrow \Pi // \mathcal{H}} \rightarrow_R^2$$

$$\frac{\mathcal{G} // \Gamma, B \Rightarrow \Delta // \mathcal{H} \quad \mathcal{G} // \Gamma, A \rightarrow B \Rightarrow \Delta, A // \mathcal{H}}{\mathcal{G} // \Gamma, A \rightarrow B \Rightarrow \Delta // \mathcal{H}} \rightarrow_L$$

$$\frac{\mathcal{G} // \Gamma, A \Rightarrow \Delta // \Sigma, A \Rightarrow \Pi // \mathcal{H}}{\mathcal{G} // \Gamma, A \Rightarrow \Delta // \Sigma \Rightarrow \Pi // \mathcal{H}} \text{Lift}$$

All other rules are local.